Neiat Olgac, Dr. Eng. Sci. Columbia Univ. 1976, M.Sc. Technical Univ. of Istanbul, Turkey 1972 (summacum-laude), both in Mechanical Engineering. He is a professor with the Mechanical Engineering Department of the University of Connecticut since 1981. His research interests are in robust nonlinear controls, active vibration absorption, time-delayed systems, micromanipulation in bio-engineering. Dr. Olgac holds three patents on the Delayed Resonator active vibration suppression technique (1995-1996-1999) and a fourth one on anti-chatter concepts in simultaneous machining (2011). He is the director of Advanced Laboratory for Robotics, Automation and Manufacturing (ALARM) at UConn. Dr. Olgac was Visiting Professor at INRIA (Sophia Antipolis, France) 1988-89, SEW Eurodrive Fellow - Guest Professor at Technical Univ. of Munich, Germany in 1995-96 and Visiting Professor at Harvard University 2002-03). He was on the editorial board of the ASME Trans. of Dynamic Systems, Measurement and Control (1996-2004), and the guest editor of the Special Issue of JDSMC on Time Delayed Systems (June, 2003), is presently on the Editorial Boards of J. Vibration and Control, Int. J. of Mechatronics and Manufacturing Systems. He was a member and the Chairman of the Executive Committee of the ASME Dynamic Systems and Control Division (2001-6). He is the General Chair of IFAC Time Delay Systems Workshop (TDS) 2012, and General Chairman of ASME Dynamic Systems and Controls Conference, DSCC2013. He is a member of the ASME Systems and Design Group Operating Board, he also sits on the A2C2 (American Automatic Control Council) Operating Board. Prof. Olgac is a member of the Connecticut Academy of Science and Engineering (CASE), Fellow of ASME and Senior Member of IEEE.